

# Appendix

## A EVALUATION RULES FOR SECTION 3

Figure 1 shows selected evaluation rules for the core language. Evaluation is based on the reduction relation  $\rightsquigarrow$ . The (unlisted) congruence rules, which evaluate a sub-expression within a larger expression, are all standard. Rule RECORD FIELD reduces a record to the expression associated with the applied label. Rule VARIANT CASE evaluates a case expression  $\text{case } l_k \text{ e of } \overrightarrow{l_i x_i \rightarrow e_i}$  over a variant by matching  $l_k \text{ e}$  with the corresponding case  $l_k x_k$ , returning  $e_k[x_k = e]$ . Rules BETA BOP, BETA UOP, and BETA EQ evaluate the built-in operators. Since the language is both confluent and strongly normalizing, the order in which we apply the evaluation rules does not matter and evaluation always terminates. We write  $\llbracket e \rrbracket$  to represent the unique term obtained by exhaustive application of the evaluation rules to  $e$ . We write  $\rightsquigarrow_*$  for the reflexive-transitive closure of  $\rightsquigarrow$ .

$$\begin{array}{c}
 \text{IF TRUE} \\
 \hline
 \text{if true then } e_1 \text{ else } e_2 \rightsquigarrow e_1 \\
 \\
 \text{IF FALSE} \\
 \hline
 \text{if false then } e_1 \text{ else } e_2 \rightsquigarrow e_2 \\
 \\
 \text{CASE VARIANT} \\
 \hline
 \text{case } l_k \text{ e of } \overrightarrow{l_i x_i \rightarrow e_i} \rightsquigarrow e'_k[x_k = e] \\
 \\
 \text{RECORD FIELD} \\
 \hline
 \overrightarrow{\{l_i = e_i\}}.l_j \rightsquigarrow e_j \\
 \\
 \text{CONG} \\
 \hline
 \frac{e \rightsquigarrow e'}{\lambda x. e \rightsquigarrow \lambda x. e'} \\
 \\
 \text{BETA} \\
 \hline
 (\lambda x. e_1) e_2 \rightsquigarrow e_1[x = e_2] \\
 \\
 \text{BETA BOP} \\
 \hline
 \text{bop } b_1 \text{ } b_2 \rightsquigarrow \text{bop}(b_1, b_2) \\
 \\
 \text{BETA UOP} \\
 \hline
 \text{uop } b \rightsquigarrow \text{uop}(b) \\
 \\
 \text{BETA EQ} \\
 \hline
 \text{eq } b_1 \text{ } b_2 \rightsquigarrow (b_1 == b_2)
 \end{array}$$

Fig. 1. Selected evaluation rules for our core language.

## B PROOFS FOR SECTION 3

PROOF OF THEOREM 3.10. We proceed by induction on the input sequence  $is$ . The base case  $[]$  is clear. For the inductive step, assume an input sequence of the form  $i : is$ . We have the chain of equalities below:

$$\begin{aligned}
 & \mathcal{M}_{(c_1, s_1)}(i : is) \\
 &=^{(1)} o : \mathcal{M}_{(c_1, s'_1)}(is) \\
 &=^{(2)} o : \mathcal{M}_{(c_2, s'_2)}(is) \\
 &=^{(3)} \mathcal{M}_{(c_2, s_2)}(i : is).
 \end{aligned}$$

Step (1) follows by definition of  $\mathcal{M}$ , where  $(s'_1, o) = \llbracket c_1(s_1, i) \rrbracket$ , and step (2) from the induction hypothesis, where  $s'_2 = \llbracket p s'_1 \rrbracket$ . Step (3) follows from the definition of  $\mathcal{M}$ , where we have the chain

of equalities below:

$$\begin{aligned}
& \llbracket c_2 (s_2, i) \rrbracket \\
& \stackrel{(1)}{=} \llbracket c_2 (p s_1, i) \rrbracket \\
& \stackrel{(2)}{=} \llbracket p c_2 (s_1, i) \rrbracket \\
& \stackrel{(3)}{=} \llbracket c_1 p (s_1, i) \rrbracket \\
& \stackrel{(4)}{=} \llbracket (s'_2, o) \rrbracket.
\end{aligned}$$

Here step (1) follows from the assumption  $p s_1 \simeq s_2$ , which means  $\llbracket p s_1 \rrbracket = \llbracket s_2 \rrbracket$ ; step (2) from the definition of  $p c_2$ ; step (3) from the assumption  $c_1 p \simeq p c_2$ ; and step (4) from the definition of  $c_1 p$ .  $\square$

**PROOF OF THEOREM 3.7.** Given circuits  $(c, s_c) : ((S, I) \rightarrow (S, O), S)$  and  $(obs, s_o) : ((S_o, O) \rightarrow (S_o, O_o), S_o)$ , we need to show that for any circuit  $(leak, s_l) : ((S_l, I) \rightarrow (S_l, O_l), S_l)$ , the two conditions below are equivalent:

(1) There exists a simulator  $(sim, s_s) : ((S_s, O_l) \rightarrow (S_s, O_o), S_s)$  such that

$$(c, s_c) \circ (obs, s_o) =_{\mathcal{M}} (leak, s_l) \circ (sim, s_s).$$

(2) For all input sequences  $is, is' : [I]$ , we have that

$$\mathcal{M}_{(leak, s_l)}(is) = \mathcal{M}_{(leak, s_l)}(is') \text{ implies } \mathcal{M}_{(c, s_c) \circ (obs, s_o)}(is) = \mathcal{M}_{(c, s_c) \circ (obs, s_o)}(is').$$

Without loss of generality, we can treat the composition  $(c, s_c) \circ (obs, s_o)$  as a monolithic circuit  $(c, s_c) : ((S, I) \rightarrow (S, O_o), S)$ .

(1) *implies* (2): The condition  $(c, s_c) =_{\mathcal{M}} (leak, s_l) \circ (sim, s_s)$  directly translates to

$$(c, s_c) =_{\mathcal{M}} (leak \circ sim, (s_l, s_s)). \quad (\star_1)$$

Fix input sequences  $is, is' : [I]$  such that

$$\mathcal{M}_{(leak, s_l)}(is') = \mathcal{M}_{(leak, s_l)}(is'). \quad (\star_2)$$

We have the chain of equalities below:

$$\begin{aligned}
& \mathcal{M}_{(c, s_c)}(is) \\
& \stackrel{(1)}{=} \mathcal{M}_{(leak \circ sim, (s_l, s_s))}(is) \\
& \stackrel{(3)}{=} \mathcal{M}_{(sim, s_s)}(\mathcal{M}_{(leak, s_l)}(is')) \\
& \stackrel{(3)}{=} \mathcal{M}_{(sim, s_s)}(\mathcal{M}_{(leak, s_l)}(is')) \\
& \stackrel{(4)}{=} \mathcal{M}_{(leak \circ sim, (s_l, s_s))}(is') \\
& \stackrel{(5)}{=} \mathcal{M}_{(c, s_c)}(is')
\end{aligned}$$

Steps (1) and (5) follow from  $(\star_1)$ ; steps (2) and (4) from Lemma B.1, and step (3) from  $(\star_2)$ .

(2) *implies* (1): Without loss of generality, we can assume that the states  $s_c, s_l$  are already in normal form. We construct a simulator as follows. Fix a term  $o_\star : O_o$ . For any core type  $s$ , let  $Terms[s]$  denote the set of closed terms  $e : s$  in normal form (that is, such that  $\llbracket e \rrbracket = e$ ). Crucially, this set is finite. To define a simulator, we need to give the internal state type  $S_s$ , the initial state  $s_s : S_s$ , and the tick function  $sim : (S_s, O_l) \rightarrow (S_s, O_o)$ .

**The Internal State Type.** Let  $\mathcal{P}(-)$  denote the power set operator on sets. Let

$$N + 1 = |\mathcal{P}(Terms[(S_l, S)])|$$

be the cardinality of the set of all subsets of closed terms of type  $(S_I, S)$  in normal form, and let

$$\phi : \{0, \dots, N\} \rightarrow \mathcal{P}(\text{Terms}[(S_I, S)])$$

be its enumeration. The state type is the record type

$$S_s := \{\text{proj}[0] : (), \dots, \text{proj}[N] : ()\}$$

That is, the internal state type of the simulator encodes all possible subsets of closed terms of type  $(S_I, S)$  in normal form. Informally, each subset represents the possible configuration of states that we reach after simultaneously running the circuits  $(\text{leak}, s_I)$  and  $(c, s_c)$  on the same input sequence.

**The Initial State.** The initial state  $s_s := \text{proj}[\phi^{-1}(\{(s_I, s_c)\})]$  corresponds to the singleton subset consisting of the initial configuration  $(s_I, s_c)$ .

**The Tick Function.** For a core type  $s$ , let  $=_s : s \rightarrow s \rightarrow \text{Bool}$  be the Boolean comparison operator that internalizes syntactic equality, *i.e.*, such that  $\llbracket e_1 =_s e_2 \rrbracket = \text{true}$  if and only if  $\llbracket e_1 \rrbracket = \llbracket e_2 \rrbracket$ . We define  $=_s$  by induction on  $s$  as follows:

- If  $s = w$  is a base type, we use the corresponding built-in comparison operator. For example, if  $w = \text{Word8}$ , we define  $=_s$  as the function  $\lambda x. \lambda y. x =_8 y$ .
- If  $s = \text{Bool}$  is the type of Booleans, we define  $=_s$  as the function

$$\lambda x. \lambda y. \text{if } x \text{ then if } y \text{ then true else false} \\ \text{else if } y \text{ then false else true}$$

- If  $s = \{l_1 : s_1, \dots, l_n : s_n\}$  is a record type, we define  $=_s$  as the function

$$\lambda x. \lambda y. \text{if } x.l_1 =_{s_1} y.l_1 \\ \text{then } \dots \text{ if } x.l_n =_{s_n} y.l_n \\ \text{then true} \\ \text{else false} \\ \text{else false.}$$

- If  $s = \langle \{l_1 : s_1, \dots, l_n : s_n\} \rangle$  is a variant type, we define  $=_s$  as the function

$$\lambda x. \lambda y. \text{case } x \text{ of} \\ \dots \\ l_i x_i \rightarrow \text{case } y \text{ of} \\ \dots \\ l_j y_j \rightarrow \begin{cases} x_i =_{s_i} y_j & \text{if } i = j \\ \text{false} & \text{if } i \neq j \end{cases} \\ \dots \\ \dots$$

Let

$$M + 1 = |\text{Terms}[(S_I, S), I]|$$

be the cardinality of the set of closed terms of type  $((S_I, S), I)$  in normal form, and let

$$\psi : \{0, \dots, M\} \rightarrow \text{Terms}[(S_I, S), I]$$

be its enumeration. We now define a function  $\text{Tick}(-, -, -)$ , whose first argument is a number  $m \in \{0, \dots, M + 1\}$ , the second is a set  $X \subseteq \text{Terms}[(S_I, S), I]$ , and the third is a set  $Y \subseteq \text{Terms}[(S_I, S)]$ . The result will be a term  $x : O_I \vdash \text{Tick}(m, X, Y) : (S_s, O_o)$ .

Given a set  $X \subseteq \text{Terms}[(S_l, S), I]$ , we define sets  $\text{RunSt}(X) \subseteq \text{Terms}[(S_l, S)]$  and  $\text{RunOut}(X) \subseteq \text{Terms}[(O_l, O_o)]$  as follows:

$$\begin{aligned} \text{RunSt}(X) &:= \{ \llbracket \text{fst}(\text{leak}(s_1, i)) \rrbracket, \llbracket \text{fst}(c(s_2, i)) \rrbracket \mid ((s_1, s_2), i) \in X \}, \\ \text{RunOut}(X) &:= \{ \llbracket \text{snd}(\text{leak}(s_1, i)) \rrbracket, \llbracket \text{snd}(c(s_2, i)) \rrbracket \mid ((s_1, s_2), i) \in X \}. \end{aligned}$$

With these definitions in place, we put:

$$\text{Tick}(m, X, Y) := \begin{cases} - (\text{proj}[\phi^{-1}(\emptyset)], o_\star) \\ \quad \text{if } m = 0 \text{ and } X = \emptyset \\ - \text{let } (\_, o) = c(s_2, i) \text{ in } (\text{proj}[\phi^{-1}(\text{RunSt}(X))], o) \\ \quad \text{if } m = 0 \text{ and } X \neq \emptyset \text{ and } \psi(m') = ((s_1, s_2), i) \text{ and } m' \text{ smallest s.t. } \psi(m') \in X \\ - \text{Tick}(m', X, Y) \\ \quad \text{if } m = m' + 1 \text{ and } \psi(m') = ((s_1, s_2), i) \text{ and } (s_1, s_2) \notin Y \\ - \text{let } (\_, o_1) = \text{leak}(s_1, i) \text{ in} \\ \quad \text{if } o_1 = o_l \text{ then } \text{Tick}(m', X \cup \{((s_1, s_2), i)\}, Y) \text{ else } \text{Tick}(m', X, Y) \\ \quad \text{if } m = m' + 1 \text{ and } \psi(m') = ((s_1, s_2), i) \text{ and } (s_1, s_2) \in Y \end{cases}$$

We define the tick function  $\text{sim} : (S_s, O_l) \rightarrow (S_s, O_o)$  as follows:

$$\text{sim} := \lambda (s_s, x). \text{ case } s_s \text{ of } \overline{\text{proj}[n] \rightarrow \text{Tick}(M+1, \emptyset, \phi(n))}.$$

**Simulator Correctness.** Given a set  $X \subseteq \text{Terms}[(S_l, S), I]$ , we define a set  $X.1 \subseteq \text{Terms}[(S_l, S)]$  as follows:

$$X.1 := \{(s_1, s_2) \mid ((s_1, s_2), i) \in X\}.$$

We call a set  $Y \subseteq \text{Terms}[(S_l, S)]$  *coherent* if the following condition holds:

- For all input sequences  $is, is' : [I]$  and all  $(s_1, s_2), (s'_1, s'_2) \in Y$ , we have that

$$\mathcal{M}_{(\text{leak}, s_1)}(is) = \mathcal{M}_{(\text{leak}, s'_1)}(is') \text{ implies } \mathcal{M}_{(c, s_2)}(is) = \mathcal{M}_{(c, s'_2)}(is').$$

To prove the Mealy equivalence  $(c, s_c) =_{\mathcal{M}} (\text{leak} \circ \text{sim}, (s_l, s_s))$ , we show the following generalization:

- If  $\phi(n)$  is coherent and  $(s_1, s_2) \in \phi(n)$ , then for any input sequence  $is : [I]$ , we have

$$\mathcal{M}_{(c, s_2)}(is) = \mathcal{M}_{(\text{leak} \circ \text{sim}, (s_1, \text{proj}[n]))}(is).$$

Since the singleton set  $\{(s_l, s_c)\}$  is coherent by assumption (this is precisely condition (2)), the instantiation of the above generalization with  $n = \phi^{-1}(\{(s_l, s_c)\})$  and  $s_1 = s_l, s_2 = s_c$  gives us the desired Mealy equivalence.

To prove the generalization, we proceed by induction on the input sequence  $is$ . The base case  $[]$  is clear. For the inductive step, assume an input sequence of the form  $i : is$ . Let  $(t_1, o_l) = \llbracket \text{leak}(s_1, i) \rrbracket$  and  $(t_2, o) = \llbracket c(s_2, i) \rrbracket$ . We now establish the following invariant: for any  $m \in \{0, \dots, M+1\}$  and sets  $X \subseteq \text{Terms}[(S_l, S), I]$ ,  $Y \subseteq \text{Terms}[(S_l, S)]$ , if

- $Y$  is coherent,
- $(s_1, s_2) \in Y$ ,
- $X.1 \subseteq Y$ ,
- $\text{RunOut}(X) \subseteq \{(o_l, o)\}$ , and
- either  $((s_1, s_2), \llbracket i \rrbracket) \in X$  or there exists an  $m' < m$  such that  $\psi(m') = ((s_1, s_2), \llbracket i \rrbracket)$ ,

then there exists an  $n' \in \{0, \dots, N\}$  such that

- $\llbracket \text{Tick}(m, X, Y)[x := o_l] \rrbracket = (\text{proj}[n'], o)$ ,

197 (g)  $\phi(n')$  is coherent, and

198 (h)  $(t_1, t_2) \in \phi(n')$ .

199 To prove this invariant, we proceed by induction on  $m$ . We consider four cases:

200 **Case 1.** If  $m = 0$  and  $X = \emptyset$ , then assumption (e) cannot be satisfied, so we are done.

201 **Case 2.** If  $m = 0$  and  $X \neq \emptyset$ , let  $n' = \phi^{-1}(\text{RunSt}(X))$ . To prove (f), let  $m'$  be the smallest natural  
 202 number such that  $\psi(m') \in X$ , and let  $((s'_1, s'_2), i') = \psi(m')$ . Let  $(t'_1, o'_1) = \llbracket \text{leak}(s'_1, i') \rrbracket$  and  $(t'_2, o'_2) =$   
 203  $\llbracket c(s'_2, i') \rrbracket$ . By assumption,  $((s'_1, s'_2), i') \in X$ , therefore  $(o'_1, o'_2) \in \text{RunOut}(X)$ . By assumption (d), we  
 204 must have  $o'_1 = o_l$  and  $o'_2 = o$ . By definition, we have

$$\begin{aligned} & \llbracket \text{Tick}(m, X, Y)[x := o_l] \rrbracket \\ &= \text{let } (\_, o) = c(s_2, i) \text{ in } (\text{proj}[\phi^{-1}(\text{RunSt}(X))], o) \\ &= (\text{proj}[\phi^{-1}(\text{RunSt}(X))], o). \end{aligned}$$

205 Thus (f) holds. To prove (g), we need to show that the set  $\text{RunSt}(X)$  is coherent. To this end, fix  
 206 sequences  $is', is'' : [I]$  and terms  $((s'_1, s'_2), i'), ((s''_1, s''_2), i'') \in X$ . Let  $(t'_1, o'_1) = \llbracket \text{leak}(s'_1, i') \rrbracket$  and  
 207  $(t'_2, o'_2) = \llbracket c(s'_2, i') \rrbracket$ . Let  $(t''_1, o''_1) = \llbracket \text{leak}(s''_1, i'') \rrbracket$  and  $(t''_2, o''_2) = \llbracket c(s''_2, i'') \rrbracket$ . We want to show that

$$\mathcal{M}_{(\text{leak}, t'_1)}(is') = \mathcal{M}_{(\text{leak}, t''_1)}(is'') \text{ implies } \mathcal{M}_{(c, t'_2)}(is') = \mathcal{M}_{(c, t''_2)}(is'').$$

208 Since by assumption  $((s'_1, s'_2), i'), ((s''_1, s''_2), i'') \in X$ , we must have  $(o'_1, o'_2), (o''_1, o''_2) \in \text{RunOut}(X)$   
 209 and  $(s'_1, s'_2), (s''_1, s''_2) \in X$ .1. Now by assumption (d), we must have  $o'_1, o''_1 = o_l$  and  $o'_2, o''_2 = o$ . And  
 210 by assumption (c), we have  $(s'_1, s'_2), (s''_1, s''_2) \in Y$ . Now assume  $\mathcal{M}_{(\text{leak}, t'_1)}(is') = \mathcal{M}_{(\text{leak}, t''_1)}(is'')$   
 211 and consider the two larger sequences  $i' : is', i'' : is''$ . By assumption (a),  $Y$  is coherent. Since  
 212  $(s'_1, s'_2), (s''_1, s''_2) \in Y$ , we have that

$$\mathcal{M}_{(\text{leak}, s'_1)}(i' : is') = \mathcal{M}_{(\text{leak}, s''_1)}(i'' : is'') \text{ implies } \mathcal{M}_{(c, s'_2)}(i' : is') = \mathcal{M}_{(c, s''_2)}(i'' : is'').$$

213 Now we have the chain of equalities below:

$$\begin{aligned} & \mathcal{M}_{(\text{leak}, s'_1)}(i' : is') \\ &=^{(1)} o_l : \mathcal{M}_{(\text{leak}, t'_1)}(is') \\ &=^{(2)} o_l : \mathcal{M}_{(\text{leak}, t''_1)}(is'') \\ &=^{(3)} \mathcal{M}_{(\text{leak}, s''_1)}(i'' : is''). \end{aligned}$$

214 Steps (1) and (3) follow by definition of  $\mathcal{M}$ , and step (2) is an earlier assumption. Therefore,  
 215  $\mathcal{M}_{(c, s'_2)}(i' : is') = \mathcal{M}_{(c, s''_2)}(i'' : is'')$ . This gives us the chain of equalities below:

$$\begin{aligned} & o : \mathcal{M}_{(c, t'_2)}(is') \\ &=^{(1)} \mathcal{M}_{(c, s'_2)}(i' : is') \\ &=^{(2)} \mathcal{M}_{(c, s''_2)}(i'' : is'') \\ &=^{(3)} o : \mathcal{M}_{(c, t''_2)}(is''). \end{aligned}$$

216 Steps (1) and (3) again follow by definition of  $\mathcal{M}$ , and step (2) is the observation above. Thus  
 217  $\mathcal{M}_{(c, t'_2)}(is') = \mathcal{M}_{(c, t''_2)}(is'')$  as desired, which proves (g). To prove (h), we note that by assumption  
 218 (e), we must have  $((s_1, s_2), \llbracket i \rrbracket) \in X$ . Therefore  $(t_1, t_2) \in \text{RunSt}(X)$  as desired.

219 **Case 3.** If  $m = m' + 1$  and  $\psi(m') = ((s'_1, s'_2), i')$  such that  $(s'_1, s'_2) \notin Y$ ,  $\text{Tick}(m, X, Y) = \text{Tick}(m', X, Y)$ .  
 220 The existence of an  $n'$  satisfying (f)–(h) follows directly from the induction hypothesis once we  
 221 establish that assumption (e) also holds for  $m'$  in place of  $m$ . From the corresponding assumption for  
 222  $m$ , we know that either  $((s_1, s_2), \llbracket i \rrbracket) \in X$  or there exists an  $m'' < m$  such that  $\psi(m'') = ((s_1, s_2), \llbracket i \rrbracket)$ .

In the first case, we are done. In the second case, we have two possibilities: either  $m'' < m'$  or  $m'' = m'$ . If  $m'' < m'$ , then we are done. If  $m'' = m'$ , then  $\psi(m') = ((s_1, s_2), \llbracket i \rrbracket)$ . From an earlier assumption, we know that  $\psi(m') = ((s'_1, s'_2), i')$  and  $(s'_1, s'_2) \notin Y$ . Thus  $s'_1 = s_1, s'_2 = s_2, i' = \llbracket i \rrbracket$ . But this means  $(s_1, s_2) \notin Y$ , which contradicts assumption (b), showing that this case is impossible.

**Case 4.** If  $m = m' + 1$  and  $\psi(m') = ((s'_1, s'_2), i')$  such that  $(s'_1, s'_2) \in Y$ , let  $(t'_1, o'_1) = \llbracket leak(s'_1, i') \rrbracket$  and  $(t'_2, o'_2) = \llbracket c(s'_2, i') \rrbracket$ . If  $o'_1 \neq o_l$ , then we have

$$\begin{aligned} & \llbracket Tick(m, X, Y)[x := o_l] \rrbracket \\ &= \llbracket \text{let } (\_, o_1) = leak(s'_1, i') \text{ in} \\ & \quad \text{if } o_1 =_{O_l} o_l \\ & \quad \quad \text{then } Tick(m', X \cup \{(s'_1, s'_2), i'\}, Y)[x := o_l] \\ & \quad \quad \text{else } Tick(m', X, Y)[x := o_l] \rrbracket \\ &= \llbracket Tick(m', X, Y)[x := o_l] \rrbracket. \end{aligned}$$

The existence of an  $n'$  satisfying (f)–(h) now follows directly from the induction hypothesis once we establish that assumption (e) also holds for  $m'$  in place of  $m$ . From the corresponding assumption for  $m$ , we know that either  $((s_1, s_2), \llbracket i \rrbracket) \in X$  or there exists an  $m'' < m$  such that  $\psi(m'') = ((s_1, s_2), \llbracket i \rrbracket)$ . In the first case, we are done. In the second case, we have two possibilities: either  $m'' < m'$  or  $m'' = m'$ . If  $m'' < m'$ , then we are done. If  $m'' = m'$ , then  $\psi(m') = ((s_1, s_2), \llbracket i \rrbracket)$ . From an earlier assumption, we know that  $\psi(m') = ((s'_1, s'_2), i')$ . Thus  $s'_1 = s_1, s'_2 = s_2, i' = \llbracket i \rrbracket$ . But this means  $t'_1 = t_1, o'_1 = o_l$ , which contradicts the assumption that  $o'_1 \neq o_l$ , showing that this case is impossible.

On the other hand, if  $o'_1 = o_l$ , then we have

$$\begin{aligned} & \llbracket Tick(m, X, Y)[x := o_l] \rrbracket \\ &= \llbracket \text{let } (\_, o_1) = leak(s'_1, i') \text{ in} \\ & \quad \text{if } o_1 =_{O_l} o_l \\ & \quad \quad \text{then } Tick(m', X \cup \{(s'_1, s'_2), i'\}, Y)[x := o_l] \\ & \quad \quad \text{else } Tick(m', X, Y)[x := o_l] \rrbracket \\ &= \llbracket Tick(m', X \cup \{(s'_1, s'_2), i'\}, Y)[x := o_l] \rrbracket. \end{aligned}$$

The existence of an  $n'$  satisfying (f)–(h) now follows directly from the induction hypothesis once we establish that assumptions (c)–(e) also hold for  $m'$  and  $X \cup \{(s'_1, s'_2), i'\}$  in place of  $m$  and  $X$ . To prove (c), we need to show that  $(s'_1, s'_2) \in Y$ . But this is precisely what we assumed earlier. To prove (d), we need to show that  $o'_1 = o_l$  and  $o' = o$ . Since we assumed that  $o'_1 = o_l$  in the first place, we only need to show  $o' = o$ . By assumption we have  $(s'_1, s'_2) \in Y$ . Furthermore, by assumption (b) we also have  $(s_1, s_2) \in Y$ . Consider the two singleton sequences  $\llbracket i \rrbracket, \llbracket i' \rrbracket$ . Since  $Y$  is coherent by assumption (a), we have that

$$\mathcal{M}_{(leak, s_1)}(\llbracket i \rrbracket) = \mathcal{M}_{(leak, s'_1)}(\llbracket i' \rrbracket) \text{ implies } \mathcal{M}_{(c, s_2)}(\llbracket i \rrbracket) = \mathcal{M}_{(c, s'_2)}(\llbracket i' \rrbracket).$$

Now

$$\mathcal{M}_{(leak, s_1)}(\llbracket i \rrbracket) = [o_l] = [o'_l] = \mathcal{M}_{(leak, s'_1)}(\llbracket i' \rrbracket).$$

Therefore, we must have

$$[o] = \mathcal{M}_{(c, s_2)}(\llbracket i \rrbracket) = \mathcal{M}_{(c, s'_2)}(\llbracket i' \rrbracket) = [o'],$$

and hence  $o' = o$ , which proves (d). To prove (e), we conclude from the corresponding assumption for  $m$  and  $X$  that we either have  $((s_1, s_2), \llbracket i \rrbracket) \in X$  or there exists an  $m'' < m$  such that  $\psi(m'') = ((s_1, s_2), \llbracket i \rrbracket)$ . In the first case, we are done. In the second case, we have two possibilities: either  $m'' < m'$  or  $m'' = m'$ . If  $m'' < m'$ , then we are done. If  $m'' = m'$ , then  $\psi(m') = ((s_1, s_2), \llbracket i \rrbracket)$ . From an earlier assumption, we know that  $\psi(m') = ((s'_1, s'_2), i')$ . Thus  $s'_1 = s_1, s'_2 = s_2, i' = \llbracket i \rrbracket$ . But this means  $((s_1, s_2), \llbracket i \rrbracket) \in X \cup \{((s'_1, s'_2), i')\}$  as desired, which proves (e). This finishes the proof of the invariant.

We now have the following:

$$\begin{aligned} & \llbracket \text{sim } (\text{proj}[n], o_l) \rrbracket \\ &= \llbracket \text{case } \text{proj}[n] \text{ of } \overrightarrow{\text{proj}[n] \rightarrow \text{Tick}(M+1, \emptyset, \phi(n)) [x := o_l]} \rrbracket \\ &= \llbracket \text{Tick}(M+1, \emptyset, \phi(n)) [x := o_l] \rrbracket. \end{aligned}$$

Using the invariant that we have just established, we conclude that there exists an  $n' \in \{0, \dots, N\}$  such that

$$\llbracket \text{Tick}(M+1, \emptyset, \phi(n)) [x := o_l] \rrbracket = (\text{proj}[n'], o),$$

with  $\phi(n')$  coherent and  $(t_1, t_2) \in \phi(n')$ , as assumptions (a)–(e) are clearly satisfied for  $m = M+1$ ,  $X = \emptyset$ ,  $Y = \phi(n)$ . We thus have

$$\llbracket \text{leak} \circ \text{sim } ((s_1, \text{proj}[n]), i) \rrbracket = ((t_1, \text{proj}[n']), o),$$

which gives us the chain of equalities below:

$$\begin{aligned} & \mathcal{M}_{(c, s_2)}(i : is) \\ &=^{(1)} o : \mathcal{M}_{(c, t_2)}(is) \\ &=^{(2)} o : \mathcal{M}_{(\text{leak} \circ \text{sim}, (t_1, \text{proj}[n']))}(is) \\ &=^{(3)} \mathcal{M}_{(\text{leak} \circ \text{sim}, (s_1, \text{proj}[n]))}(i : is). \end{aligned}$$

Step (1) follows by definition of  $\mathcal{M}$ ; step (2) from the induction hypothesis, using that  $\phi(n')$  is coherent and  $(t_1, t_2) \in \phi(n')$ ; and step (3) from what we have just shown. This finishes the proof.  $\square$

**PROOF OF LEMMA 3.11.** Given circuits  $(c, s_c) : ((S, I) \rightarrow (S, O), S)$  and  $(obs, s_o) : ((S_o, O) \rightarrow (S_o, O_o), S_o)$ , we need to show that for any circuit  $(leak, s_l) : ((S_l, I) \rightarrow (S_l, O_l), S_l)$  and function  $p : (S, S_o) \rightarrow (S_l, S_s)$ , the two conditions below are equivalent:

- (1) There exists a simulator  $(sim, s_s) : ((S_s, O_l) \rightarrow (S_s, O_o), S_s)$  such that

$$(c, s_c) \circ (obs, s_o) \hookrightarrow (leak, s_l) \circ (sim, s_s)$$

via the state projection function  $p$ .

- (2) The following non-interference properties hold:

(2.1) **Initial State Correspondence:** We have  $\llbracket \text{fst } (p(s_c, s_o)) \rrbracket = \llbracket s_l \rrbracket$ .

(2.2) **Tick State Correspondence:** For all  $((s_1, s_2), i) : ((S, S_o), I)$ , we have

$$\begin{aligned} & \llbracket \text{let } ((t_1, t_2), \_) = c \circ obs((s_1, s_2), i) \text{ in let } (v_1, \_) = p(t_1, t_2) \text{ in } v_1 \rrbracket = \\ & \llbracket \text{let } (u_1, \_) = p(s_1, s_2) \text{ in let } (v_1, \_) = leak(u_1, i) \text{ in } v_1 \rrbracket. \end{aligned}$$

(2.3) **Projection Coherence:** For all  $((s_1, s_2), i), ((s'_1, s'_2), i') : ((S, S_o), I)$ , if

$$\begin{aligned} & \llbracket \text{let } (u_1, u_2) = p(s_1, s_2) \text{ in let } (\_, o_1) = leak(u_1, i) \text{ in } (u_2, o_1) \rrbracket = \\ & \llbracket \text{let } (u'_1, u'_2) = p(s'_1, s'_2) \text{ in let } (\_, o'_1) = leak(u'_1, i') \text{ in } (u'_2, o'_1) \rrbracket \end{aligned}$$

then we have

$$\begin{aligned} \llbracket \text{let } ((t_1, t_2), o_o) = c \circ \text{obs } ((s_1, s_2), i) \text{ in let } (\_, v_2) = p(t_1, t_2) \text{ in } (v_2, o_o) \rrbracket = \\ \llbracket \text{let } ((t'_1, t'_2), o'_o) = c \circ \text{obs } ((s'_1, s'_2), i) \text{ in let } (\_, v'_2) = p(t'_1, t'_2) \text{ in } (v'_2, o'_o) \rrbracket. \end{aligned}$$

Without loss of generality, we can treat the composition  $(c, s_c) \circ (\text{obs}, s_o)$  as a monolithic circuit  $(c, s_c) : ((S, I) \rightarrow (S, O_o), S)$ .

(1) *implies* (2): By assumption,  $p$  is the state projection function witnessing the reduction  $(c, s_c) \hookrightarrow (\text{leak}, s_l) \circ (\text{sim}, s_s)$ . Recall the definitions

$$\begin{aligned} c_1 p &= \lambda (s, i). \text{let } (t, o) = c(s, i) \text{ in } (p t, o), \\ p c_2 &= \lambda (s, i). \text{leak} \circ \text{sim } (p s, i). \end{aligned}$$

Then we have  $p s_c \simeq (s_l, s_s)$  and  $c_1 p \simeq p c_2$ . To prove (2.1), we need to show  $\llbracket \text{fst } (p s_c) \rrbracket = \llbracket s_l \rrbracket$ . As  $p s_c \simeq (s_l, s_s)$ , we have  $\llbracket p s_c \rrbracket = \llbracket (s_l, s_s) \rrbracket = (\llbracket s_l \rrbracket, \llbracket s_s \rrbracket)$ . Therefore,  $\llbracket \text{fst } (p s_c) \rrbracket = \llbracket s_l \rrbracket$  as desired. To show (2.2), fix term  $(s, i) : (S, I)$ . Let  $(t, o) = \llbracket c(s, i) \rrbracket$ ,  $(u_1, u_2) = \llbracket p s \rrbracket$ ,  $(v_1, v_2) = \llbracket p t \rrbracket$ . Let  $(w_1, o_l) = \llbracket \text{leak}(u_1, i) \rrbracket$  and  $(w_2, o_s) = \llbracket \text{sim}(u_2, o_l) \rrbracket$ . The condition

$$\begin{aligned} \llbracket \text{let } (t, \_) = c(s, i) \text{ in let } (v_1, \_) = p t \text{ in } v_1 \rrbracket = \\ \llbracket \text{let } (u_1, \_) = p s \text{ in let } (v_1, \_) = \text{leak}(u_1, i) \text{ in } v_1 \rrbracket \end{aligned}$$

reduces to  $v_1 = w_1$ . Since  $c_1 p \simeq p c_2$ , we have  $\llbracket c_1 p(s, i) \rrbracket = \llbracket p c_2(s, i) \rrbracket$ . This implies

$$((v_1, v_2), o) = \llbracket c_1 p(s, i) \rrbracket = \llbracket p c_2(s, i) \rrbracket = ((w_1, w_2), o_s).$$

Therefore  $w_1 = v_1$  as desired. To prove (2.3), fix terms  $(s, i), (s', i') : (S, I)$ . Let  $(t, o) = \llbracket c(s, i) \rrbracket$  and  $(t', o') = \llbracket c(s', i') \rrbracket$ . Let  $(u_1, u_2) = \llbracket p s \rrbracket$  and  $(u'_1, u'_2) = \llbracket p s' \rrbracket$ . Let  $(v_1, v_2) = \llbracket p t \rrbracket$  and  $(v'_1, v'_2) = \llbracket p t' \rrbracket$ . Let  $(w_1, o_l) = \llbracket \text{leak}(u_1, i) \rrbracket$  and  $(w'_1, o'_l) = \llbracket \text{leak}(u'_1, i') \rrbracket$ . Let  $(w_2, o_s) = \llbracket \text{sim}(u_2, o_l) \rrbracket$  and  $(w'_2, o'_s) = \llbracket \text{sim}(u'_2, o'_l) \rrbracket$ . Assume that

$$\begin{aligned} \llbracket \text{let } (u_1, u_2) = p s \text{ in let } (\_, o_1) = \text{leak}(u_1, i) \text{ in } (u_2, o_1) \rrbracket = \\ \llbracket \text{let } (u'_1, u'_2) = p s' \text{ in let } (\_, o'_1) = \text{leak}(u'_1, i') \text{ in } (u'_2, o'_1) \rrbracket. \end{aligned}$$

The above condition reduces to  $(u_2, o_l) = (u'_2, o'_l)$ , which implies  $(w'_2, o'_s) = (w_2, o_s)$ . We want to show that

$$\begin{aligned} \llbracket \text{let } (t, o) = c(s, i) \text{ in let } (\_, v_2) = p t \text{ in } (v_2, o) \rrbracket = \\ \llbracket \text{let } (t', o') = c(s', i') \text{ in let } (\_, v'_2) = p t' \text{ in } (v'_2, o') \rrbracket. \end{aligned}$$

The above condition reduces to  $(v_2, o) = (v'_2, o')$ . Since  $c_1 p \simeq p c_2$ , we have  $\llbracket c_1 p(s, i) \rrbracket = \llbracket p c_2(s, i) \rrbracket$  and  $\llbracket c_1 p(s', i') \rrbracket = \llbracket p c_2(s', i') \rrbracket$ . This implies

$$\begin{aligned} ((v_1, v_2), o) = \llbracket c_1 p(s, i) \rrbracket = \llbracket p c_2(s, i) \rrbracket = ((w_1, w_2), o_s), \\ ((v'_1, v'_2), o') = \llbracket c_1 p(s', i') \rrbracket = \llbracket p c_2(s', i') \rrbracket = ((w'_1, w'_2), o'_s). \end{aligned}$$

We thus have  $v'_2 = w'_2 = w_2 = v_2$  and  $o' = o'_s = o_s = o$  as desired.

(2) *implies* (1): Fix a term  $o_\star : O_o$ . As in the proof of Theorem 3.7, let  $\text{Terms}[s]$ , where  $s$  is a core type, denote the set of closed terms  $e : s$  in normal form. To define a simulator, we need to give the initial state  $s_s : S_s$  and the tick function  $\text{sim} : (S_s, O_l) \rightarrow (S_s, O_o)$ .

**The Initial State.** The initial state  $s_s := \text{snd}(p s_c)$  is the simulator part of the projected initial state  $s_c$  of the original circuit.

**The Tick Function.** For a core type  $s$ , let  $=_s : s \rightarrow s \rightarrow \text{Bool}$  be the comparison operator that internalizes syntactic equality, as defined in the proof of Theorem 3.7. Let  $M + 1 = |\text{Terms}[(S, I)]|$  be the cardinality of the set of closed terms of type  $(S, I)$  in normal form, and let  $\psi : \{0, \dots, M\} \rightarrow$

393  $Terms[(S, I)]$  be its enumeration. We now define a function  $Tick(-)$ , whose argument is a number  
 394  $m \in \{0, \dots, M + 1\}$ . The result will be a term  $x : S_s, y : O_l \vdash Tick(m) : (S_s, O_o)$ .

$$395 \quad Tick(m) := \begin{cases} 396 & - (x, o_\star) \quad \text{if } m = 0 \\ 397 & - \text{let } (u_1, u_2) = p \ s \ \text{in let } (\_, o_1) = leak \ (u_1, i) \ \text{in} \\ 398 & \quad \text{if } (u_2, o_1) =_{(S_s, O_l)} (x, y) \\ 399 & \quad \quad \text{then let } (t, o) = c \ (s, i) \ \text{in let } (\_, v_2) = p \ t \ \text{in } (v_2, o) \\ 400 & \quad \quad \text{else } Tick(m', X, Y) \\ 401 & \quad \quad \text{if } m = m' + 1 \ \text{and } \psi(m') = (s, i) \end{cases}$$

403 We define the tick function  $sim : (S_s, O_l) \rightarrow (S_s, O_o)$  as  $sim := \lambda (x, y). Tick(M + 1)$ .

404 **Simulator Correctness.** Recall the definitions

$$405 \quad c_1 p = \lambda (s, i). \text{let } (t, o) = c \ (s, i) \ \text{in } (p \ t, o), \\ 406 \quad pc_2 = \lambda (s, i). leak \circ sim \ (p \ s, i).$$

408 To show that  $(c, s_c) \hookrightarrow (leak, s_l) \circ (sim, s_s)$  via the state projection function  $p$ , we need to show that  
 409  $p \ s_c \simeq (s_l, s_s)$  and  $c_1 p \simeq pc_2$ . To establish that  $p \ s_c \simeq (s_l, s_s)$ , we need to show that  $\llbracket p \ s_c \rrbracket = \llbracket (s_l, s_s) \rrbracket$ .  
 410 Let  $(u_1, u_2) = \llbracket p \ s_c \rrbracket$ . From condition (2.1), we know that  $\llbracket \text{fst } (p \ s_c) \rrbracket = \llbracket s_l \rrbracket$ . We thus have

$$411 \quad \llbracket p \ s_c \rrbracket = (u_1, u_2) = (\llbracket \text{fst } (p \ s_c) \rrbracket, \llbracket \text{snd } (p \ s_c) \rrbracket) = (\llbracket s_l \rrbracket, \llbracket s_s \rrbracket) = \llbracket (s_l, s_s) \rrbracket$$

413 as desired. To show  $c_1 p \simeq pc_2$ , it suffices to prove that for any term  $(s, i) : Terms[(S, I)]$ , we have  
 414  $\llbracket c_1 p \ (s, i) \rrbracket = \llbracket pc_2 \ (s, i) \rrbracket$ . To this end, let  $(t, o) = \llbracket c \ (s, i) \rrbracket$ ,  $(u_1, u_2) = \llbracket p \ s \rrbracket$ ,  $(v_1, v_2) = \llbracket p \ t \rrbracket$ , and  
 415  $(w_1, o_l) = \llbracket leak \ (u_1, i) \rrbracket$ . We now establish the following invariant: for any  $m \in \{0, \dots, M + 1\}$ , if

- 416 • there exists an  $m' < m$  such that  $\psi(m') = (s, i)$ ,

418 then we have

- 419 •  $\llbracket Tick(m)[x := u_2, y := o_l] \rrbracket = (v_2, o)$ .

420 To prove this invariant, we proceed by induction on  $m$ .

421 **Case 1.** If  $m = 0$ , then the assumption cannot be satisfied, so we are done.

422 **Case 2.** If  $m = m' + 1$  and  $\psi(m') = (s', i')$ , let  $(t', o') = \llbracket c \ (s', i') \rrbracket$ ,  $(u'_1, u'_2) = \llbracket p \ s' \rrbracket$ ,  $(o'_1, o'_2) = \llbracket p \ t' \rrbracket$ ,  
 423 and  $(w'_1, o'_l) = \llbracket leak \ (u'_1, i') \rrbracket$ . If  $(u'_2, o'_l) \neq (u_2, o_l)$ , then we have

$$424 \quad \llbracket Tick(m)[x := u_2, y := o_l] \rrbracket \\ 425 \quad = \llbracket \text{let } (u_1, u_2) = p \ s' \ \text{in let } (\_, o_1) = leak \ (u_1, i') \ \text{in} \\ 426 \quad \quad \text{if } (u_2, o_1) =_{(S_s, O_l)} (u_2, o_l) \\ 427 \quad \quad \quad \text{then let } (t, o) = c \ (s', i') \ \text{in let } (\_, v_2) = p \ t \ \text{in } (v_2, o) \\ 428 \quad \quad \quad \text{else } Tick(m')[x := u_2, y := o_l] \rrbracket \\ 429 \quad = \llbracket Tick(m')[x := u_2, y := o_l] \rrbracket.$$

430 The conclusion now follows directly from the induction hypothesis once we establish that the  
 431 assumption also holds for  $m'$  in place of  $m$ . From the corresponding assumption for  $m$ , we know  
 432 that there exists an  $m'' < m$  such that  $\psi(m'') = (s, i)$ . Now either  $m'' < m'$  or  $m'' = m'$ . If  $m'' < m'$ ,  
 433 then we are done. If  $m'' = m'$ , then  $\psi(m') = (s, i)$ . From an earlier assumption, we know that  
 434  $\psi(m') = (s', i')$ . Thus  $s' = s, i' = i$ . But this means  $u'_1 = u_1, u'_2 = u_2$  and  $w'_1 = w_1, o'_l = o_l$ , which  
 435 contradicts the assumption that  $(u'_2, o'_l) \neq (u_2, o_l)$ , showing that this case is impossible.

On the other hand, if  $(u'_2, o'_l) = (u_2, o_l)$ , then we have

$$\begin{aligned}
& \llbracket \text{Tick}(m)[x := u_2, y := o_l] \rrbracket \\
&= \llbracket \text{let } (u_1, u_2) = p \text{ s' in let } (\_, o_1) = \text{leak } (u_1, i') \text{ in} \\
&\quad \text{if } (u_2, o_1) =_{(s_s, o_l)} (u_2, o_l) \\
&\quad \quad \text{then let } (t, o) = c (s', i') \text{ in let } (\_, v_2) = p \text{ t in } (v_2, o) \\
&\quad \quad \text{else } \text{Tick}(m')[x := u_2, y := o_l] \rrbracket \\
&= (v'_2, o').
\end{aligned}$$

From condition (2.3), we know that if

$$\begin{aligned}
& \llbracket \text{let } (u_1, u_2) = p \text{ s in let } (\_, o_1) = \text{leak } (u_1, i) \text{ in } (u_2, o_1) \rrbracket = \\
& \llbracket \text{let } (u'_1, u'_2) = p \text{ s' in let } (\_, o'_1) = \text{leak } (u'_1, i') \text{ in } (u'_2, o'_1) \rrbracket
\end{aligned}$$

then we have

$$\begin{aligned}
& \llbracket \text{let } (t, o) = c (s, i) \text{ in let } (\_, v_2) = p \text{ t in } (v_2, o) \rrbracket = \\
& \llbracket \text{let } (t', o') = c (s', i') \text{ in let } (\_, v'_2) = p \text{ t' in } (v'_2, o') \rrbracket.
\end{aligned}$$

In other words,  $(u_2, o_l) = (u'_2, o'_l)$  implies  $(v'_2, o') = (v_2, o)$ . Since we assumed that  $(u'_2, o'_l) = (u_2, o_l)$  in the first place, we have  $(v'_2, o') = (v_2, o)$ , which finishes the proof of the invariant.

Using the invariant that we have just established, we conclude that

$$\llbracket \text{sim } (u_2, o_l) \rrbracket = \llbracket \text{Tick}(M+1)[x := u_2, y := o_l] \rrbracket = (v_2, o),$$

as the invariant assumption is clearly satisfied for  $m = M+1$ . We thus have

$$\llbracket \text{leak } \circ \text{sim } ((u_1, u_2), i) \rrbracket = ((w_1, v_2), o).$$

The condition  $\llbracket c_1 p (s, i) \rrbracket = \llbracket p c_2 (s, i) \rrbracket$  now reduces to showing that  $((v_1, v_2), o) = ((w_1, v_2), o)$ . To show  $v_1 = w_1$ , we recall that from condition (2.2), we know that

$$\begin{aligned}
& \llbracket \text{let } (t, \_) = c (s, i) \text{ in let } (v_1, \_) = p \text{ t in } v_1 \rrbracket = \\
& \llbracket \text{let } (u_1, \_) = p \text{ s in let } (v_1, \_) = \text{leak } (u_1, i) \text{ in } v_1 \rrbracket.
\end{aligned}$$

The above condition reduces precisely to  $v_1 = w_1$ , which finishes the proof.  $\square$

**Lemma B.1.** For circuits  $(c_1, s_1) : ((S_1, I_1) \rightarrow (S_1, O_1), S_1)$  and  $(c_2, s_2) : ((S_2, O_1) \rightarrow (S_2, O_2), S_2)$ , and an input sequence is :  $[I]$ , we have

$$\mathcal{M}_{(c_1, s_1) \circ (c_2, s_2)}(is) = \mathcal{M}_{(c_2, s_2)}(\mathcal{M}_{(c_1, s_1)}(is)).$$

## C COMPLETE PROCESSOR CODE FOR ??

**Fetch Stage.** The fetch stage (Listing 2) decodes the raw instruction and updates the program counter based on the previous instruction's execution. It stores the decoded instruction in the state's `exInstr` field and the current program counter (needed when executing a `Beq` instruction) in `exPC`; these become state inputs to execute stage in the next cycle. If a jump occurred in the previous cycle (i.e., `jmp` is a `Just`-value), the instruction is discarded and is replaced with a no-op (`Add 0`). Otherwise, the program counter is incremented by 1.

**Case Study Processor.** The full processor (Listing 1) is composed of all the pipeline stages. The pipeline executes stages in reverse order—writeback, then execute, then fetch—to prevent overwriting stage state inputs before they are used.

```

491 1 proc :: (State, Word16) -> (State, (Maybe Word32, Word8))
492 2
493 3 proc (state0, rawInstr) = do
494 4   let (state1, out) = writeback (state0, ())
495 5   let (state2, jmp) = execute (state1', ())
496 6   let (state3, _) = fetch (state2, (rawInstr, jmp))
497 7   (state3, (out, pc state3))

```

Listing 1. The Pipelined Processor.

```

501 1 fetch :: (State, (Word16, Maybe Word8)) -> State
502 2 fetch (state@State { fePC }, (rawInstr, jump)) = do
503 3   let (exInstr, fePC') = case jump of
504 4       Just jmpPC -> (Add 0, jmpPC) -- Add 0 == no-op
505 5       Nothing -> (decode rawInstr, fePC + 1)
506 6   state { exPC = fePC, exInstr, fePC = fePC' }

```

Listing 2. Fetch Stage.

```

510 1 writeback :: (State, ()) -> (State, Maybe Word32)
511 2 writeback (state@State { reg, wbRes, wbOut }, _) = do
512 3   let reg' = case wbRes of Just value -> value; Nothing -> reg
513 4   (state { reg = reg' }, wbOut)

```

Listing 3. Writeback Stage.

```

517 1 sim :: (SState, LInstr) -> (SState, Word8)
518 2 sim (SState { fePC, exPC }, leakInstr) = do
519 3   let fePC' = case leakInstr of
520 4       LJmp addr -> addr
521 5       LBr off -> exPC + off
522 6       LOther -> fePC + 1
523 7   (SState { exPC = fePC, fePC = fePC' }, fePC')

```

Listing 4. Simulator.

**Writeback Stage.** The writeback stage (Listing 3) updates the register value in the processor state and returns the output.

**Simulator.** The simulator executes the leakage instructions and outputs the current program counter. The leakage instructions only specify when they are branching, for the remaining instructions we simply increment the program counter.

## D EXAMPLE: STATE PROJECTION RULE

*Example (Counterexample to Completeness of State Projection).* Let the implementation circuit have trivial state, input, and output:  $S = ()$ ,  $I = ()$ ,  $O = ()$ .

```

537 1 impl :: ((), ()) -> ((), ())

```

538

539

540 1 `impl (_, _) = ((), ())`

541 Let the leakage circuit alternate between two internal states:

$$542 \quad S_\ell = \{s_1, s_2\}, \quad I_\ell = (), \quad O_\ell = ().$$

544 `leak :: (S_1, ()) -> (S_1, ())`

545 `leak (s1, _) = (s2, ())`

546 `leak (s2, _) = (s1, ())`

547 Any state projection  $p : S \rightarrow S_\ell$  must fix one state:  $p () = s1$  and hence remains constant  
 548 over time. However, `leak` switches between `s1` and `s2` on each step. Thus, no  $p$  satisfies the state  
 549 projection rule, even though their Mealy transducers are I/O-equivalent.

## 550 E REPLICATED RESULTS FROM LEAVE.

| Benchmark     | Time (min.) | Replicated | Reported |
|---------------|-------------|------------|----------|
| RE            |             | 0.5        | 1.5      |
| DarkRISCV-2   |             | 3.5        | 7.2      |
| DarkRISCV-3   |             | 10.0       | 11.1     |
| Sodor-2       |             | 31.4       | 97.8     |
| Ibex-small    |             | 825.3      | 1479.4   |
| Ibex-cache    |             | 1030.1     | 1396.7   |
| Ibex-mult-div |             | 673.4      | 1291.9   |

560 Table 1. Replicated runtimes from LeaVe.

561

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564 Table 1 only presents the replicated benchmark results of LeaVe directly used for our comparison.  
 565 We present the full set of results from LeaVe in Table 1.

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